

## ROBOTICS

<b>Course code</b>	20ME2702B	<b>Year</b>	IV	<b>Semester</b>	I
<b>Course category</b>	Open Elective-4	<b>Offering Branch</b>	ME	<b>Course Type</b>	Theory
<b>Credits</b>	3	<b>L-T-P</b>	3-0-0	<b>Prerequisites</b>	Nil
<b>Continuous Internal Evaluation</b>	30	<b>Semester End Evaluation</b>	70	<b>Total Marks</b>	100

	<b>Statement</b>	<b>Level</b>
<b>CO1</b>	Understand the basic anatomy of robots, actuators, end effectors, robot sensors, programming and applications.	L2
<b>CO2</b>	Understand the working principles of robot actuators, end effectors	L2
<b>CO3</b>	Apply robot programming skills	L3
<b>CO4</b>	Apply knowledge of robot sensors and their applications in industries	L3

### Contribution of Course Outcomes towards achievement of Program Outcomes & Strength of correlations (3: High, 2: Medium, 1:Low)

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
<b>CO1</b>	3												3	1
<b>CO2</b>	3	3											3	1
<b>CO3</b>	3	3	2		2								3	1
<b>CO4</b>	3		2										3	1

### Syllabus

<b>UNIT NO</b>	<b>Contents</b>	<b>Mapped COs</b>
<b>I</b>	<b>Introduction:</b> Automation and robotics – History of robots -Robot anatomy – classification of robots, major components-robot specifications, selection of robots.	<b>CO1</b>
<b>II</b>	<b>Robot actuators-</b> Pneumatic, Hydraulic actuators, electric & stepper motors <b>End Effectors-</b> types of end effectors, grippers and tools, Requirements and challenges of end effectors.	<b>CO1, CO2</b>
<b>III</b>	<b>Robot Programming:</b> - Robot programming languages - programming methods - off and on-line programming - Lead through method - Teach	<b>CO1, CO3</b>

	pendent method, simple programs.	
<b>IV</b>	<b>Sensors used in robots:</b> Sensor devices, Types of sensors - contact, position and displacement sensors, Force and torque sensors - Proximity and range sensors - acoustic sensors –slip sensors, Robot vision systems	<b>CO1, CO4</b>
<b>V</b>	<b>Applications of robots:</b> Application of robots in industry - material handling, processing operations, assembly, and inspection operations.	<b>CO1, CO4</b>

### Learning Resource

#### **Text books:**

1. Mikell P. Groover. Industrial Robotics Technology Programming and Applications, McGraw Hill Co., Singapore, 1995.
2. Robotic Engineering by Richard D.Klafter, Prentice Hall

#### **Reference books**

1. Introduction to Robotics – Saeed B.Niku, Prentice Hall
2. Introduction to Robotics – John J. Craig, Addison Wesley

#### **E-Resources & other digital Material:**

1. <http://nptel.ac.in/downloads/112101098/>