| CourseCode | 20ME5605 | Year | III | Semester | II |
|--------------------------------------|-------------|-------------------------------|-------|---------------|---------------------------|
| Course Category | Minor in AE | Branch | ME | Course Type | Theory |
| Credits | 4 | L - T - P | 3-1-0 | Prerequisites | Automobile Engineering |
| Continuous Internal Evaluation | 30 | Semester End Evaluation | 70 | Total Marks | 100 |

AUTONOMOUS VEHICLES

Course Outcomes: Upon successful completion of the course, the student will be able to

| | Statement | Skill | BTL | Units |
|-----|---|------------|-----|-----------|
| C01 | Understand technology and advancements applied in and connected, Automated and intelligent Cars | Understand | L2 | 1,2,3,4,5 |
| CO2 | Apply knowledge of sensor and wireless technology to execute systems in connected and autonomous cars | Apply | L3 | 2,3,5 |
| CO3 | Analyze and critically evaluate the safety challenges associated with future vehicles to rate the ethical implications of alternative automotive technologies | Analyze | L4 | 1,4,5 |

| | Co | ontribu | | | | | | | | of Prog um, 1:I | _ | Outcom | es & | |
|------------|-----|---------|-----|-----|-----|-----|-----|-----|-----|--------------------|------|--------|------|------|
| | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 |
| CO1 | 3 | | 3 | | 3 | 1 | 2 | 2 | | 2 | | 2 | 3 | 2 |
| CO2 | 3 | | 3 | | 3 | 1 | 2 | | | 2 | | 2 | 3 | 2 |
| CO3 | 3 | | 3 | | 2 | 1 | 2 | 3 | | 2 | | 2 | 3 | 2 |

| Syllabus | | | | |
|----------|--|---------------|--|--|
| UNIT | Contents | Mapped COs | | |
| I | Introduction To Connected, Automated And Intelligent Cars Introduction to Connected, automated and Intelligent cars- Automotive Electronics Overview, Advanced Driver Assistance Electronic Systems, Connected Car Technology- Connectivity Fundamentals, Navigation and Other Applications, Connected and Autonomous Vehicle Technology Basic Control System Theory applied to Automobiles, Overview of the Operation of ECUs, Basic Cyber-Physical System Theory. | CO1 CO3 | | |
| п | Sensor Technology Sensor Technology for Advanced Driver Assistance Systems- Basics of Radar Technology and Systems, Ultrasonic Sonar Systems, Lidar Sensor Technology and Systems, Camera Technology, Night Vision Technology, Impaired Driver Technology Driver Impairment Sensor Technology, Sensor Technology for Driver Impairment Detection, Transfer of Control Technology | CO1 CO2 | | |
| III | Introduction to Self-Driving Vehicle Technology | CO1 | | |

| | Eundomentals of state of the art SI AM multi sensor date fusion and | CO2 |
|----|---|------------|
| | Fundamentals of state-of-the-art SLAM, multi-sensor data fusion, and other SDV algorithms, Bohot Operating System (BOS) and Operation | 002 |
| | other SDV algorithms. Robot Operating System (ROS) and Open | |
| | Source Car Control (OSCC). | |
| | Wireless System Standards and Standards Organizations | |
| | Wireless Networking and Applications to Vehicle Autonomy: Basics | |
| | of Computer Networking – the Internet of Things, Wireless Networking | |
| | Fundamentals, Integration of Wireless Networking and On-Board | |
| | Vehicle Networks | |
| | Acceptance, Security And Ethics Of Autonomous Driving | |
| | Why Ethics Matters for Autonomous Driving, Opportunities and Risks | |
| | Associated with Autonomous Driving, User / public Acceptance of | |
| IV | Autonomous Driving | CO1 |
| | Regulations, Policies And Standards Of Autonomous Driving | CO3 |
| | | |
| | | 005 |
| | Regulatory bodies for highly automated and autonomous driving, | 005 |
| | Regulatory bodies for highly automated and autonomous driving, Policies and policy making in autonomous driving, Autonomous | 00 |
| | Regulatory bodies for highly automated and autonomous driving, Policies and policy making in autonomous driving, Autonomous driving, standardization bodies and standards | |
| | Regulatory bodies for highly automated and autonomous driving, Policies and policy making in autonomous driving, Autonomous driving, standardization bodies and standardsRecent Driver Assistance System And Vehicles | |
| | Regulatory bodies for highly automated and autonomous driving, Policies and policy making in autonomous driving, Autonomous driving, standardization bodies and standardsRecent Driver Assistance System And Vehicles Recent Driver Assistance System Technology- Basics of Theory of | |
| | Regulatory bodies for highly automated and autonomous driving, Policies and policy making in autonomous driving, Autonomous driving, standardization bodies and standardsRecent Driver Assistance System And Vehicles Recent Driver Assistance System Technology- Basics of Theory of Operation, Applications – Legacy, Applications – New | C01 |
| v | Regulatory bodies for highly automated and autonomous driving, Policies and policy making in autonomous driving, Autonomous driving, standardization bodies and standardsRecent Driver Assistance System And Vehicles Recent Driver Assistance System Technology- Basics of Theory of Operation, Applications – Legacy, Applications – New Future Applications | CO1 CO2 |
| v | Regulatory bodies for highly automated and autonomous driving, Policies and policy making in autonomous driving, Autonomous driving, standardization bodies and standardsRecent Driver Assistance System And Vehicles Recent Driver Assistance System Technology- Basics of Theory of | C01 |
| v | Regulatory bodies for highly automated and autonomous driving, Policies and policy making in autonomous driving, Autonomous driving, standardization bodies and standards Recent Driver Assistance System And Vehicles Recent Driver Assistance System Technology- Basics of Theory of Operation, Applications – Legacy, Applications – New Future Applications Integration of ADAS Technology into Vehicle Electronics, System Examples, Role of Sensor Data Fusion, Recent Driver Assistance | CO1 CO2 |
| V | Regulatory bodies for highly automated and autonomous driving, Policies and policy making in autonomous driving, Autonomous driving, standardization bodies and standardsRecent Driver Assistance System And Vehicles Recent Driver Assistance System Technology- Basics of Theory of Operation, Applications – Legacy, Applications – New Future Applications Integration of ADAS Technology into Vehicle Electronics, System | CO1 CO2 |

Learning Resources

| Text books |
|--|
| 1.George Dimitrakopoulos, Aggelos Tsakanikas, Elias Panagiotopoulos, "Autonomous |
| Vehicles Technologies, Regulations, and Societal Impacts", Elsevier Publications, 2021. |
| 2.Dietmar P.F. Möller, Roland E. Haas, Guide to Automotive Connectivity and |
| Cybersecurity: Trends, Technologies, 2019, Springer Publications. |
| 3.Hanky Sjafrie, "Introduction to Self-Driving Vehicle Technology", 1st Edition, Published |
| December 11, 2019 by Chapman and Hall/CRC |
| Reference books |
| 1.G. Mullett, Wireless Telecommunications Systems and Networks, Thomson - Delmar |
| Learning, ISNB#1-4018-8659-0, 2006 |
| 2. G. Mullett, Basic Telecommunications: The Physical Layer, Thomson – Delmar Learning, |
| ISBN#1-4018-4339-5, 2003 |

3.Tom Denton, Automobile Electrical and Electronic Systems, 3rd Edition Elsevier Publications 2004.